

Design and Optimization of Plate Girders and Weld-fabricated Beams for Building Construction

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Currently, design of plate girders and weld-fabricated beams necessitates an iteration of trial designs to establish the web-buckling range used in analysis.

The material presented here illustrates an expeditious mathematical and nomographic design method for bi-symmetric plate girders and weld-fabricated beams, as well as material-optimization for any given moment-shear combination. The method shown is based on the web-buckling theory (no tension-field action), and on the assumption of flange configurations that do not necessitate bending-stress reductions in the compression flange. Design examples are given numerically and shown on nomographs.

CROSS-SECTIONAL PROPERTIES

In general terms, a girder's moment of inertia can be expressed as follows (see Fig. 1):

$$I = d^2 \frac{A_w}{12} + 2 \left(\frac{d-h}{2} \right)^2 \frac{A_f}{12} + 2 \left(\frac{d+h}{4} \right)^2 A_f \quad (1)$$

Developed:

$$I = \frac{d^2}{12} \times [A (1 + \phi + \phi^2) - d t \phi (1 + \phi)] \quad (2)$$

Hence:

$$S = \frac{d}{6} \times [A (1 + \phi + \phi^2) - d t \phi (1 + \phi)] \quad (3)$$

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Re-arranging:

$$A = \frac{1}{1 + \phi + \phi^2} \times \left[\frac{6 S}{d} + d t \phi (1 + \phi) \right] \quad (4)$$

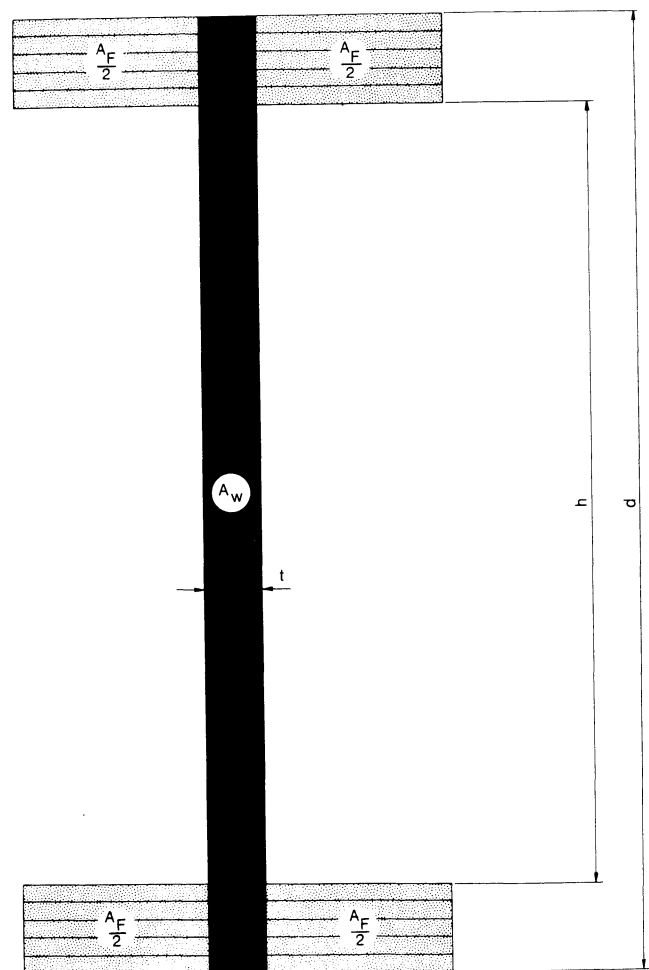


Figure 1

Substituting: $A_f = \frac{A - d t}{2}$

$$A_f = \frac{1}{1 + \phi + \phi^2} \times \left(\frac{3 S}{d} - \frac{d t}{2} \right) \quad (5)$$

Very close results can be obtained by the simplifying approximations $(1 + \phi + \phi^2) = 3 \phi$ and $(1 + \phi) = 2 \phi^{1/2}$, which will reduce the cross-sectional property equations to:

$$S = d \phi \left(\frac{A}{2} - \frac{d t \phi^{1/2}}{3} \right) \quad (3a)$$

$$A = \frac{2 S}{d \phi} + \frac{2 d t \phi^{1/2}}{3} \quad (4a)$$

$$A_f = \frac{S}{d \phi} - \frac{d t}{6 \phi} \quad (5a)$$

FLANGE DESIGN NOTES

To avoid reductions of allowable stresses in the compression flange, the following AISC Specification¹ requirements have to be met:

1. $\frac{b}{t_f}$ is to be smaller than $\frac{190}{F_y^{1/2}}$ (Sect. 1.9.1)
2. $\frac{h}{t}$ is to be smaller than $\frac{760}{(0.6 F_y)^{1/2}}$ (Sect. 1.10.6)

To qualify as a fully compact compression flange:

3. $\frac{b}{t_f}$ is to be smaller than $\frac{130}{F_y^{1/2}}$ (Sect. 1.5.1.4.1-(2))

In all cases, a laterally supported compression flange is assumed.

SPECIFICATION REQUIREMENTS

Plate girder design is governed by the following AISC Specification¹ requirements:

$$f_v = \frac{V}{d t} \quad (\text{Sect. 1.5.1.2.1}) \quad (6)$$

$$F_v = \frac{F_y}{2.89} (C_v) \leq 0.40 F_y \quad (\text{Eq. 1.10-1}) \quad (7)$$

where $C_v = \frac{45,000 k t^2}{F_y h^2}$ when C_v is less than 0.8 (7a)

$$= \frac{60 t}{h} \left(\frac{10 k}{F_y} \right)^{1/2} \quad \text{when } C_v \text{ is more than } 0.8^* \quad (7b)$$

in which

$$k = 4.00 + \frac{5.34 h^2}{a^2} \quad \text{when } \frac{a}{h} \text{ is less than } 1.0$$

$$= 5.34 + \frac{4.00 h^2}{a^2} \quad \text{when } \frac{a}{h} \text{ is more than } 1.0$$

$$= 5.34 \quad \text{when } \frac{a}{h} \text{ is more than } 3.0^{**}$$

in which a is the clear distance between stiffeners, in.

$$\frac{h}{t} \leq \frac{14,000}{[F_y(F_y + 16.5)]^{1/2}} \quad (\text{Sect. 1.10.2}) \quad (8)$$

$$\frac{h}{t} \leq 260 \quad (\text{Sect. 1.10.5.3}) \quad (9)$$

$$\frac{h}{t} \leq \frac{760}{(0.6 F_y)^{1/2}} \quad \text{for no reduction in flange stress (Sect. 1.10.6)} \quad (10)$$

$$\frac{h}{t} \leq \frac{640}{F_y^{1/2}} \quad \text{for compact web}^{***} \quad (11)$$

(Sect. 1.5.1.4.1-(4))

Note:

Eq. 7a equals Eq. 7b at $\frac{h}{t} = 75 \times \left(\frac{10 k}{F_y} \right)^{1/2} \quad (12)$

Eq. 7 equals $0.4 F_y$ at $\frac{h}{t} = \frac{150}{2.89} \times \left(\frac{10 k}{F_y} \right)^{1/2} \quad (13)$

Eq. 10 governs over Eq. 8 for $F_y < 187$

Eq. 10 governs over Eq. 9 for $F_y > 14$

WEB DESIGN—GENERAL CONDITION

Plate girder webs fall into one of the following five buckling ranges:

1. $F_v = 0.4 \times F_y$ (for convenience, this will be called "plastic buckling")
2. C_v is more than 0.8 (compact web, inelastic buckling)
3. C_v is less than 0.8 and Eq. 11 applies (compact web, elastic buckling)
4. C_v is less than 0.8 and Eq. 10 applies (non-compact web, elastic buckling)

*The exact value of $60 \times 10^{1/2}$ is used in lieu of the approximate value of 190 used in the AISC Specification.¹

**This represents "Accepted Engineering Practice."

***The buckling parameter $\frac{h}{t}$ is used in lieu of the ratio $\frac{d}{t}$ used in the AISC Specification.¹

5. C_v is less than 0.8 and Eq. 10 is exceeded (reduction in compression flange allowable bending stress—not considered herein)

The applicable range is found by the following algebraic manipulations:

1. Combine Eq. 6 = $0.4 F_y$ with h/t to be equal to or smaller than Eq. 13

$$\frac{V}{d t} = 0.4 F_y \quad \text{and} \quad \frac{h}{t} \leq \frac{150}{2.89} \times \left(\frac{10 k}{F_y} \right)^{1/2}$$

2. Combine Eq. 6 = Eq. 7 using Eq. 7b with h/t to be equal to or smaller than Eq. 12

$$\frac{V}{d t} = \frac{F_y}{2.89} \times \frac{60 t}{h} \times \left(\frac{10 k}{F_y} \right)^{1/2} \quad \text{and}$$

$$\frac{h}{t} \leq 75 \times \left(\frac{10 k}{F_y} \right)^{1/2}$$

3. Combine Eq. 6 = Eq. 7 using Eq. 7a with Eq. 11

$$\frac{V}{d t} = \frac{F_y}{2.89} \times \frac{45,000 k t^2}{F_y h^2} \quad \text{and} \quad \frac{h}{t} \leq \frac{640}{F_y^{1/2}}$$

4. Combine Eq. 6 = Eq. 7 using Eq. 7a with Eq. 10

$$\frac{V}{d t} = \frac{F_y}{2.89} \times \frac{45,000 k t^2}{F_y h^2} \quad \text{and}$$

$$\frac{h}{t} \leq \frac{760}{(0.6 F_y)^{1/2}}$$

5. Not considered in this paper

The results of these operations will be:

$$1. V \geq \frac{d^2 F_y^{3/2} \phi}{948.2} \times \left(\frac{5.34}{k} \right)^{1/2} \quad (\text{plastic-compact}) \quad (14a)$$

$$2. V \geq \frac{d^2 F_y^{3/2} \phi}{1,980} \times \left(\frac{5.34}{k} \right)^{1/2} \quad (\text{inelastic-compact}) \quad (14b)$$

$$3. V \geq \frac{d^2 F_y^{3/2} \phi}{3,153} \times \left(\frac{k}{5.34} \right) \quad (\text{elastic-compact}) \quad (14c)$$

$$4. V \geq \frac{d^2 F_y^{3/2} \phi}{11,360} \times \left(\frac{k}{5.34} \right) \quad (\text{elastic-non-compact}) \quad (14d)$$

$$5. V < \frac{d^2 F_y^{3/2} \phi}{11,360} \times \left(\frac{k}{5.34} \right) \quad (\text{not considered}) \quad (14e)$$

WEB DESIGN

For plastic buckling:

Take Eq. 6 $\leq 0.4 F_y$ and solve for t :

$$\frac{V}{d t} \leq 0.4 F_y \quad \text{therefore} \quad (15a)$$

$$t \geq 2.5 \times \frac{V}{d F_y}$$

For inelastic buckling:

Take Eq. 6 to be equal to or smaller than Eq. 7 using Eq. 7b and solve for t :

$$\frac{V}{d t} \leq \frac{F_y}{2.89} \times \frac{60 t}{h} \times \left(\frac{10 k}{F_y} \right)^{1/2} \quad \text{therefore} \quad (15b)$$

$$t \geq 0.1234 \times \frac{V^{1/2} \phi^{1/2}}{k^{1/4} F_y^{1/4}}$$

For elastic buckling:

Take Eq. 6 to be equal to or smaller than Eq. 7 using Eq. 7a and solve for t :

$$\frac{V}{d t} \leq \frac{F_y}{2.89} \times \frac{45,000 k t^2}{F_y h^2} \quad \text{therefore} \quad (15c)$$

$$t \geq 0.0400 \times \frac{V^{1/3} d^{1/3} \phi^{2/3}}{k^{1/3}}$$

$$\text{In general:} \quad t \geq m V^{(1-n)/2} d^n \quad (16)$$

with values for m and n from Table 1.

GENERAL DESIGN PROCEDURE

Given: S , V , d , F_y , k , ϕ

1. Compare V with Eqs. 14a – 14e to establish the range
2. Obtain t_{min} from Eqs. 15a – 15c according to the range
3. Choose $t \geq t_{min}$
4. Obtain $A_{f min}$ from either Eq. 5 or Eq. 5a
5. Choose $A_f > A_{f min}$ observing the “Flange Design Notes”
6. Obtain net weight of girder from $w = (2 A_f + d t) \times 3.4$, plf

Example 1:

$$\begin{array}{ll} S = 1,600 \text{ in.}^3 & V = 300 \text{ kips} \\ d = 60 \text{ in.} & F_y = 36 \text{ ksi} \\ k = 5.34 & \phi = 0.96 \end{array}$$

$$1. 14a: V \geq 787 ? \text{ No}$$

$$14b: V \geq 377 ? \text{ No}$$

$$14c: V \geq 237 ?$$

Yes; therefore: compact web – elastic buckling

$$2. t_{min} = 0.584 \text{ in.}$$

$$3. \text{ Take } t = 0.625 \text{ in.}$$

$$4. A_{f min} = 21.3 \text{ in.}^2$$

$$5. \text{ Take } A_f = 17.125 \times 1.25 = 21.4 \text{ in.}^2 \\ \text{check for compactness:}$$

$$\left(\frac{17.125 + 0.625}{1.25} = 14.2 \right) < \left(\frac{130}{36^{1/2}} = 21.7 \right) \text{ o.k.}$$

$$6. w = (2 \times 21.4 + 60 \times 0.625) \times 3.4 = 273 \text{ plf}$$

MATERIAL OPTIMIZATION

For the cross-sectional dimensions encountered in practice, the ratio $h/d = \phi$ has very little influence on optimization results and can be treated as a constant. Introducing Eq. 16 into Eq. 4 will result in a general formulation of the girder cross-sectional area:

$$A = \frac{1}{1 + \phi + \phi^2} \times \left[\frac{6S}{d} + m\phi(1 + \phi) V^{(1-n)/2} d^{(1+n)} \right] \quad (17)$$

in which S , V and ϕ are given; m and n are obtainable from Table 1 for the given values of F_y , k and ϕ ; and d is unknown.

To obtain the minimum area, the first derivative $\frac{\partial A}{\partial d}$ has to equal zero and the second derivative $\frac{\partial^2 A}{\partial d^2}$ has to be positive:

$$\frac{\partial A}{\partial d} = \frac{1}{1 + \phi + \phi^2} \times \left[-\frac{6S}{d^2} + (1 + n)m\phi(1 + \phi) \times V^{(1-n)/2} d^n \right] = 0 \quad (18)$$

$$\frac{\partial^2 A}{\partial d^2} = \frac{1}{1 + \phi + \phi^2} \times \left[\frac{12S}{d^3} + n(1 + n)m\phi(1 + \phi) \times V^{(1-n)/2} d^{(n-1)} \right] > 0$$

Solving Eq. 18 for d will result in the most economical girder depth:

$$d^* = \left[\frac{6S}{(1 + n)m\phi(1 + \phi)V^{(1-n)/2}} \right]^{1/(2+n)} \quad (19)$$

Eq. 19 can now be used to obtain other girder parameters. Introducing Eq. 19 into Eq. 16 will indicate the most economical web thickness:

$$t^* = m^{2/(2+n)} V^{(1-n)/(2+n)} \left[\frac{6S}{(1 + n)\phi(1 + \phi)} \right]^{n/(2+n)} \quad (20)$$

Introducing Eq. 19 into Eq. 17 will show the material-optimized cross-sectional area:

$$A^* = \frac{2 + n}{1 + \phi + \phi^2} \times \left(\frac{6S}{1 + n} \right)^{(1+n)/(2+n)} \times V^{(1-n)/[2 \times (2+n)]} \times [m\phi(1 + \phi)]^{1/(2+n)} \quad (21)$$

Eq. 19 divided by Eq. 20 results in the optimized d/t ratio:

$$\frac{d^*}{t^*} = \left(\frac{1}{m} \right)^{3/(2+n)} \times \left[\frac{6S}{(1 + n)\phi(1 + \phi)V^{3/2}} \right]^{(1-n)/(2+n)} \quad (22)$$

Eq. 19 times Eq. 21 results in:

$$A^* d^* = \frac{6S}{1 + \phi + \phi^2} \times \frac{2 + n}{1 + n} \quad (23)$$

Eq. 19 squared times Eq. 20 will yield:

$$d^{*2} t^* = \frac{6S}{(1 + n)\phi(1 + \phi)} \quad (24)$$

Eq. 19 times Eq. 20 divided by Eq. 21 shows the most economical web area – total area ratio:

$$\frac{d^* t^*}{A^*} = \frac{1 + \phi + \phi^2}{(2 + n)\phi(1 + \phi)} \quad (25)$$

Note that Eqs. 23-25 do not contain web shear V ; in addition, Eq. 25 is independent from the section modulus S .

The most economical depth given by Eq. 19 is not very sensitive to optimization, as will be shown in the following:

By multiplying Eq. 17 with the girder depth d and dividing by Eq. 23, the following expression ensues:

$$\frac{A d}{A^* d^*} = \frac{1+n}{2+n} \times \left[1 + \frac{m \phi (1+\phi) V^{(1-n)/2} d^{(2+n)}}{6 S} \right] \quad (26)$$

Re-arranging:

$$\frac{A}{A^*} = \frac{1+n}{2+n} \times \left[\frac{d^*}{d} + \frac{d^{*(2+n)}}{d^{*(1+n)}} \times \frac{m \phi (1+\phi) V^{(1-n)/2} d^{(1+n)}}{6 S} \right] \quad (27)$$

Raising Eq. 19 to the $(2+n)$ power and introducing it into Eq. 27 will give the ratio of the cross-sectional areas of the non-optimized girder to the optimized girder:

$$\frac{A}{A^*} = \frac{1}{2+n} \times \left[\frac{d^*}{d} (1+n) + \left(\frac{d}{d^*} \right)^{(1+n)} \right] \quad (28)$$

Fig. 2 shows the weight increases if the chosen girder depth differs from the optimized depth. It demonstrates that even substantial changes in girder depths do not affect girder economy appreciably.

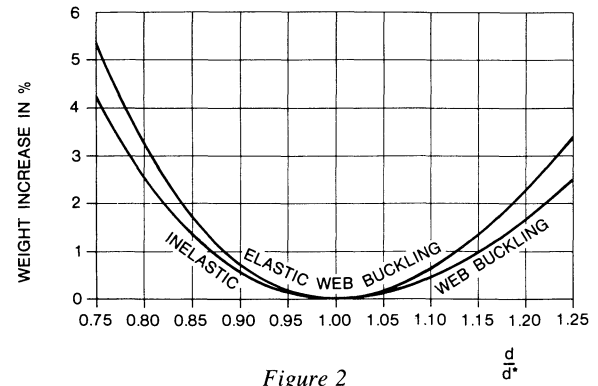


Figure 2

By introducing the values for n and m from Table 1 into Eqs. 19-28 and using the previously recommended approximations $(1+\phi+\phi^2) = 3\phi$ and $(1+\phi) = 2\phi^{1/2}$, the working equations given in Table 2 are obtained.

Table 1

Web buckling	n	m
Plastic	-1	$\frac{2.5}{F_y}$
Inelastic	0	$0.1234 \times \left(\frac{\phi^2}{k F_y} \right)^{1/4}$
Elastic	$\frac{1}{3}$	$0.0400 \times \left(\frac{\phi^2}{k} \right)^{1/3}$

Table 2

Dimension or property	Inelastic Web Buckling	Elastic Web Buckling	Equation
d^*	$4.930 \left(\frac{S^2 k^{1/2} F_y^{1/2}}{V \phi^4} \right)^{1/4}$	$5.621 \left(\frac{S^3 k}{V \phi^{13/2}} \right)^{1/7}$	(19)
t^*	$0.1234 \left(\frac{V^2 \phi^2}{k F_y} \right)^{1/4}$	$0.0712 \left(\frac{S V^2 \phi^{5/2}}{k^2} \right)^{1/7}$	(20)
A^*	$0.8113 \left(\frac{S^2 V}{k^{1/2} F_y^{1/2}} \right)^{1/4}$	$0.6226 \left(\frac{S^4 V}{k \phi^{1/2}} \right)^{1/7}$	(21)
$\frac{d^*}{t^*}$	$39.95 \left(\frac{S^2 k^{3/2} F_y^{3/2}}{V^3 \phi^6} \right)^{1/4}$	$78.95 \left(\frac{S^2 k^3}{V^3 \phi^9} \right)^{1/7}$	(22)
$A^* d^*$	$\frac{4 S}{\phi}$	$\frac{7 S}{2 \phi}$	(23)
$d^{*2} t^*$	$\frac{3 S}{\phi^{3/2}}$	$\frac{9 S}{4 \phi^{3/2}}$	(24)
$\frac{d^* t^*}{A^*}$	$\frac{3}{4 \phi^{1/2}}$	$\frac{9}{14 \phi^{1/2}}$	(25)
$\frac{A}{A^*}$	$\frac{1}{2} \left[\frac{d}{d^*} + \frac{d^*}{d} \right]$	$\frac{1}{7} \left[3 \left(\frac{d}{d^*} \right)^{4/3} + 4 \frac{d^*}{d} \right]$	(28)

WEB DESIGN—OPTIMIZED CONDITION

The following combinations of equations are used to determine the limits of the buckling ranges, paralleling those for the General Condition:

- 2a. Combine Eq. 13 and Eq. 22 times ϕ to obtain the lower limit for inelastic web buckling (compact):

$$\frac{h}{t} = 39.95 \frac{S^{1/2} k^{3/8} F_y^{3/8}}{V^{3/4} \phi^{1/2}} \quad \text{and}$$

$$\frac{h}{t} \geq \frac{150}{2.89} \times \left(\frac{10 k}{F_y} \right)^{1/2}$$

- 2b. Combine Eq. 12 and Eq. 22 times ϕ to obtain the upper limit for inelastic web buckling (compact):

$$\frac{h}{t} = 39.95 \frac{S^{1/2} k^{3/8} F_y^{3/8}}{V^{3/4} \phi^{1/2}} \quad \text{and}$$

$$\frac{h}{t} \leq 75 \times \left(\frac{10 k}{F_y} \right)^{1/2}$$

- 3a. Combine Eq. 12 and Eq. 22 times ϕ to obtain the lower limit for elastic web buckling (compact):

$$\frac{h}{t} = 78.95 \frac{S^{2/7} k^{3/7}}{V^{3/7} \phi^{2/7}} \quad \text{and}$$

$$\frac{h}{t} \geq 75 \left(\frac{10 k}{F_y} \right)^{1/2}$$

- 3b. Combine Eq. 11 and Eq. 22 times ϕ to obtain the upper limit for elastic web buckling (compact):

$$\frac{h}{t} = 78.95 \frac{S^{2/7} k^{3/7}}{V^{3/7} \phi^{2/7}} \quad \text{and}$$

$$\frac{h}{t} \leq \left(\frac{640}{F_y^{1/2}} \right)$$

4. Combine Eq. 10 and Eq. 22 times ϕ to obtain the upper limit for elastic web buckling (non-compact, $F_b = 0.6 F_y$):

$$\frac{h}{t} = 78.95 \frac{S^{2/7} k^{3/7}}{V^{3/7} \phi^{2/7}} \quad \text{and}$$

$$\frac{h}{t} \leq \frac{760}{(0.6 F_y)^{1/2}}$$

The results will be:

$$\left. \begin{aligned} 2a. \quad \frac{S^2 F_y^{7/2}}{V^3 \phi^2} &\geq 658 \left(\frac{k}{5.34} \right)^{1/2} \\ 2b. \quad \frac{S^2 F_y^{7/2}}{V^3 \phi^2} &\leq 2,870 \left(\frac{k}{5.34} \right)^{1/2} \end{aligned} \right\} \quad \begin{matrix} (29a) \\ (29b) \end{matrix} \quad \left(\begin{matrix} \text{inelastic-} \\ \text{compact} \end{matrix} \right)$$

$$\left. \begin{aligned} 3a. \quad \frac{S^2 F_y^{7/2}}{V^3 \phi^2} &\geq 5,100 \left(\frac{k}{5.34} \right)^{1/2} \\ 3b. \quad \frac{S^2 F_y^{7/2}}{V^3 \phi^2} &\leq 15,100 \left(\frac{5.34}{k} \right)^3 \end{aligned} \right\} \quad \begin{matrix} (29c) \\ (29d) \end{matrix} \quad \left(\begin{matrix} \text{elastic-} \\ \text{compact} \end{matrix} \right)$$

$$4. \quad \frac{S^2 F_y^{7/2}}{V^3 \phi^2} \leq 301,000 \left(\frac{5.34}{k} \right)^3 \quad \left(\begin{matrix} \text{elastic-} \\ \text{non-compact} \end{matrix} \right) \quad (29e)$$

No optimization is possible below the limit of Eq. 29a and between the limits of Eqs. 29b and 29c.

OPTIMIZED DESIGN PROCEDURE

The required result of this procedure is to obtain a girder weight which is a minimum for given values of S , V , F_y , k and ϕ . This procedure is carried out as follows.

1. Compare $\frac{S^2 F_y^{7/2}}{V^3 \phi^2}$ with Eqs. 29a-29e to establish the range

If elastic web buckling governs, proceed as follows:

2. Obtain t^* from (Eq. 20 – elastic) in Table 2
3. Choose $t \approx t^*$
4. Obtain d_{max} from Eq. 15c :
$$d_{max} = 83,150 \frac{t^3}{V \phi^2} \times \left(\frac{k}{5.34} \right)$$
5. Choose $d \leq d_{max}$
6. Obtain $A_{f min}$ from either Eq. 5 or Eq. 5a
7. Choose $A_f \geq A_{f min}$ observing the Flange Design Notes
8. Obtain net weight of girder from $w = (2 A_f + d t) \times 3.4$, plf

Example 2:

$$S = 1,600 \text{ in.}^3 \quad V = 300 \text{ kips} \quad F_y = 36 \text{ ksi}$$

$$k = 5.34 \quad \phi = 0.98$$

1. $\frac{S^2 F_y^{7/2}}{V^3 \phi^2} = 27,600$ (elastic – non-compact)
2. $t^* = 0.641 \text{ in.}$
3. Take $t = 0.625 \text{ in.}$
4. $d_{max} = 70.5 \text{ in.}$
5. Take $d = 70 \text{ in.}$
6. $A_{f min} = 15.9 \text{ in.}^2$
7. Take $A_f = 16 \times 1 = 16.0 \text{ in.}^2$
check for flange stress reduction:

$$\left(\frac{16 + 0.625}{1} = 16.6 \right) < (190/36^{1/2} = 31.7)$$

$$(68/0.625 = 109) < [760/(0.6 \times 36)^{1/2} = 164] \quad \text{o.k.}$$

$$8. w = (2 \times 16 + 70 \times 0.625) \times 3.4 = 258 \text{ plf}$$

If inelastic web buckling governs, proceed as follows:

2. Obtain t^* from Eq. 20 – inelastic in Table 2
3. Choose $t \geq t^*$
4. Obtain d^* from Eq. 24 – inelastic in Table 2:

$$d^* = \left(\frac{3 S}{t \phi^{3/2}} \right)^{1/2}$$

5. Choose $d \approx d^*$ but $\frac{2.5 V}{t F_y} < d < \frac{3.61 V}{t F_y}$ from Eq. 15a, and Eq. 15b introduced into Eq. 14b, respectively
6. Obtain $A_{f \min}$ from either Eq. 5 or Eq. 5a
7. Choose $A_f \geq A_{f \min}$ observing the Flange Design Notes
8. Obtain net weight of girder from $w = (2 A_f + d t) \times 3.4$, plf

Example 3:

$$S = 300 \text{ in.}^3 \quad V = 290 \text{ kips} \quad F_y = 36 \text{ ksi}$$

$$k = 5.34 \quad \phi = 0.97$$

1. $\frac{S^2 F_y^{7/2}}{V^3 \phi^2} = 1,100$ (inelastic – compact)
2. $t^* = 0.556$ in.
3. Take $t = 0.5625$ in. (9/16 in.)
4. $d^* = 41$ in.
5. Take $d = 40$ in. ($36 < 40 < 52$)
6. $A_{f \min} = 3.86 \text{ in.}^2$
7. Take $A_f = 6.9375 \times 0.5625 = 3.90 \text{ in.}^2$
check for compactness:
 $[(6.9375 + 0.5625)/0.5625 = 13.3] < [130/(36)^{1/2} = 21.7]$ **o.k.**
8. $w = (2 \times 3.9 + 40 \times 0.5625) \times 3.4 = 103 \text{ plf}$

NOMOGRAPHIC SOLUTIONS

(For $k = 5.34$, i.e., unstiffened webs)

The following nomographs will expedite design because the required parameters can be obtained with minimal calculations. As before, the examples will demonstrate the general and material-optimized conditions.

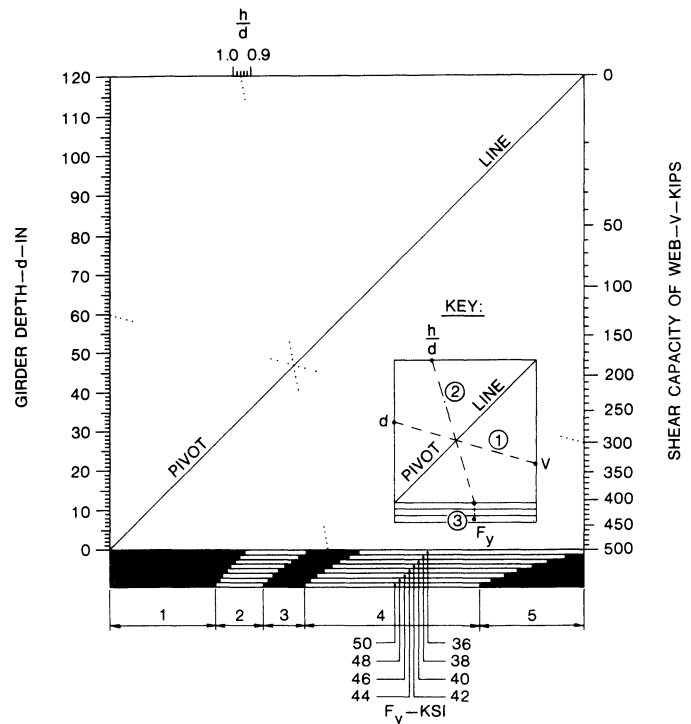
General Condition: (girder depth d is given)

1. Find the range from Graph 1
2. Find t_{\min} from General Condition graph for corresponding range
3. Continue at Step 3 of General Design Procedure

Optimized Condition (elastic):

1. Find the range from Graph 5
2. Find $t \approx (t^* \text{ from Graph 7})$
3. Find $d_{\max} = (d \text{ from Graph 4})$
4. Continue at Step 5 of Optimized Design Procedure – elastic

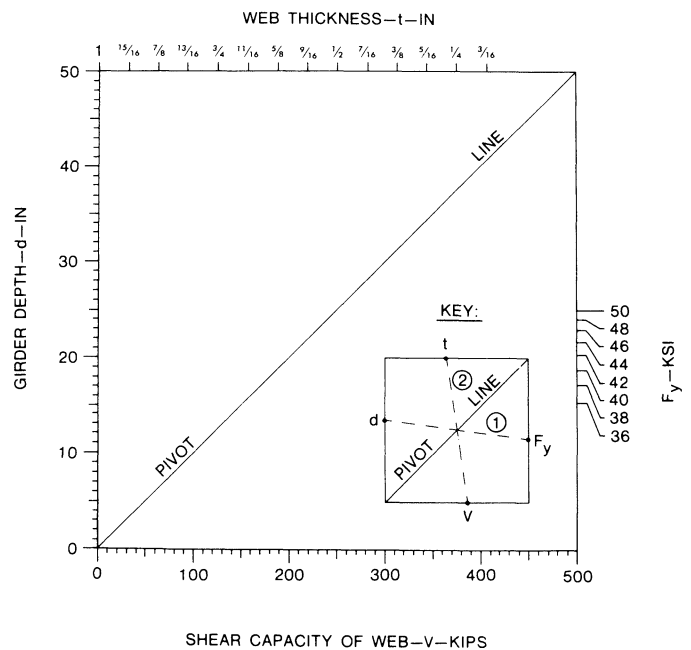
Graph 1



GENERAL CONDITION

- RANGE 1: $F_v = 0.4 F_y$
 RANGE 2: $C_v \geq 0.8$ (COMPACT WEB—INELASTIC BUCKLING)
 RANGE 3: $C_v < 0.8$ (COMPACT WEB—ELASTIC BUCKLING)
 RANGE 4: $C_v < 0.8$ (NONCOMPACT WEB—ELASTIC BUCKLING)
 RANGE 5: $C_v < 0.8$ (REDUCTION IN ALLOW. COMPR. FLG. STRESS)

Graph 2

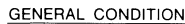


SHEAR CAPACITY OF WEB—V—KIPS

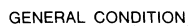
GENERAL CONDITION

- RANGE 1: $F_v = 0.4 F_y$

WEB THICKNESS—t—IN



WEB THICKNESS— t —IN

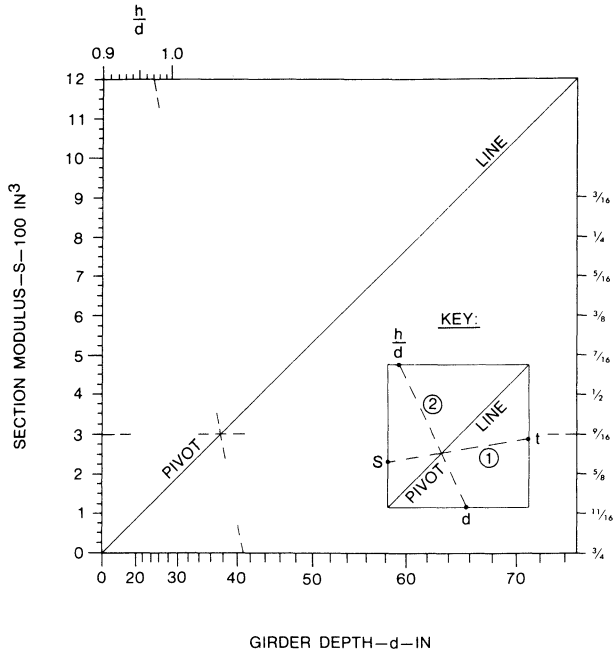


Graph 5



The techniques presented allow the designer to obtain material sizes for plate girders and weld-fabricated beams directly, either mathematically or nomographically. Trial designs are not necessary to establish web-buckling ranges. The developed design approaches can be used for general as well as for material-optimized design situations.

Graph 6

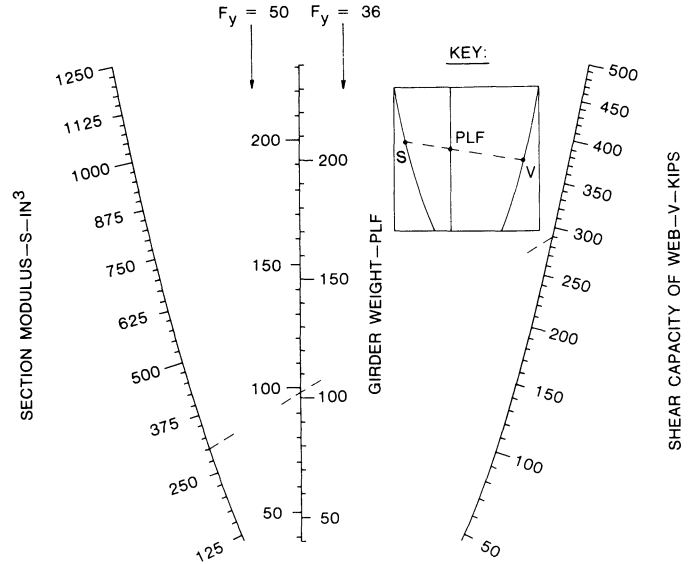


GIRDER DEPTH—d—IN

OPTIMIZED CONDITION

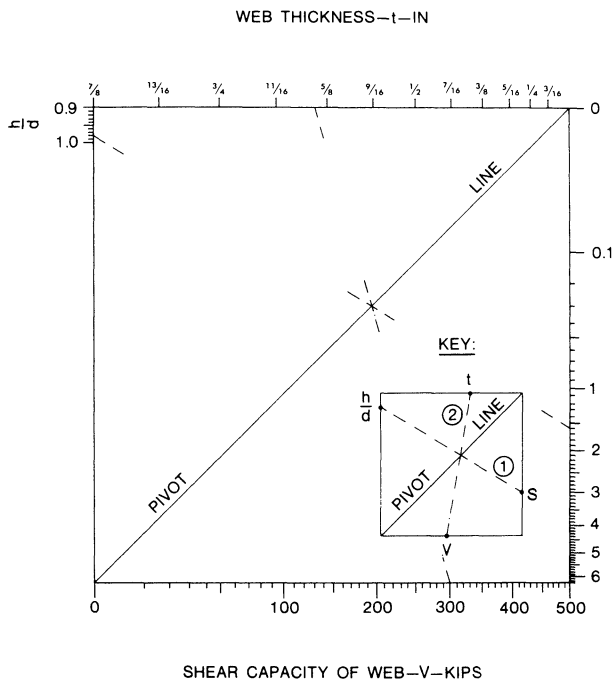
RANGE 2 •• : $C_v \geq 0.8$ (COMPACT WEB—INELASTIC BUCKLING)

Graph 8



WEIGHT OF GIRDER FOR RANGE 2 ••
OPTIMIZED CONDITION— $C_v \geq 0.8$

Graph 7

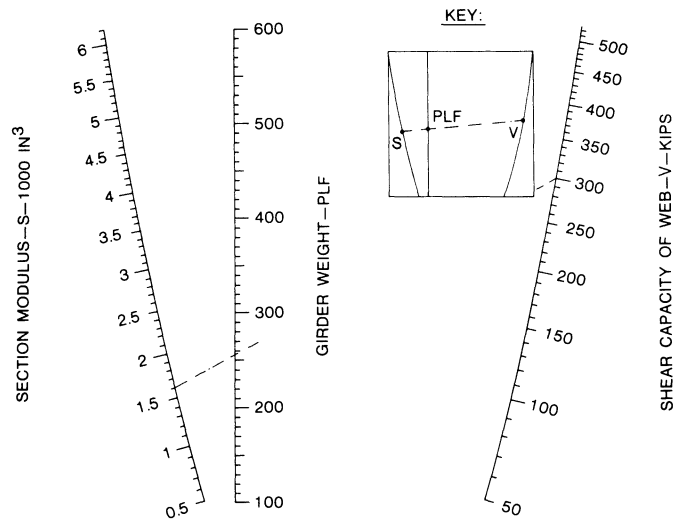


SHEAR CAPACITY OF WEB—V—KIPS

OPTIMIZED CONDITION

RANGES 3, 4, 5: $C_v < 0.8$ (ELASTIC WEB BUCKLING)

Graph 9



WEIGHT OF GIRDER FOR RANGES 3 & 4
OPTIMIZED CONDITION— $C_v < 0.8$

REFERENCES

1. American Institute of Steel Construction, Inc. Specification for the Design, Fabrication and Erection of Structural Steel for Buildings Chicago, Ill., Nov. 1, 1978.

NOMENCLATURE (unless given in text)

A	= cross-sectional total area of girder—chosen, in. ²
A^*	= cross-sectional total area of girder—material optimized, in. ²
A_f	= cross-sectional area of one flange as shown in Fig. 1, in. ²
A_w	= cross-sectional area of web as shown in Fig. 1, in. ²
F_b	= allowable bending stress in flange, ksi
F_v	= allowable shear stress in web, ksi
F_y	= yield stress, ksi
I	= moment of inertia of girder, in. ⁴
S	= section modulus of girder—furnished, in. ³
V	= shear force capacity of web—furnished, kips
b	= full nominal width of flange, in.
d	= depth of girder—furnished, or chosen, in.
d^*	= depth of girder—material optimized, in.

f_v	= shear stress in web, ksi
h	= clear distance between top and bottom flanges, in.
t	= web thickness—chosen, in.
t^*	= web thickness—material optimized, in.
t_f	= flange thickness, in.
w	= net weight of girder (= 3.4 A), plf
ϕ	= h/d , furnished

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